

## Features

- I<sup>2</sup>C-bus to 16-bit GPIO expander
- Operating power supply voltage from 1.65 V to 5.5 V
- Low standby current consumption:
  - 3.0  $\mu$ A (typical at 5 V  $V_{CC}$ )
  - 1.5  $\mu$ A (typical at 3.3 V  $V_{CC}$ )
- 400 kHz Fast-mode I<sup>2</sup>C-bus
- 5 V tolerant I/Os
- Open-drain active LOW interrupt output (INT)
- Configurable Slave Address with 3 Address Pins
- Internal power-on reset
- Power-up with all channels configured as inputs with weak pull-up resistors
- Latch-Up performance exceeds 200 mA per JESD 78
- ESD Protection Exceeds JESD 22
  - 4000-V Human Body Model
  - 1500-V Charged Device Model

## Applications

- Servers/Storages
- Routers (Telecom Switching Equipment)
- Personal Computers

## Description

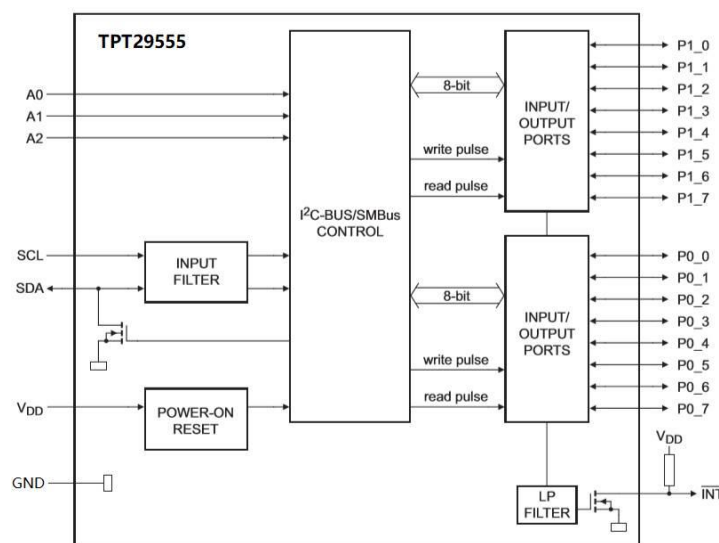
The TPT29555 is a 16-bit GPIO expander with interrupt and weak pull-up resistors for I<sup>2</sup>C-bus applications. The power supplier voltage range is from 1.65 V to 5.5 V that allows the TPT29555 to interconnect with 1.8-V microcontrollers.

The TPT29555 contains the register set of two pairs of 8-bit Configuration, Input, Output, and Polarity Inversion registers. The open-drain interrupt (INT) output is changeable when any input state changes from its related register state and is used to indicate the system master that an input state has changed. INT can be connected to the interrupt input of a microcontroller. By sending an interrupt signal on this line, the remote I/O can inform the microcontroller if there is incoming data on its ports without having to communicate via the I<sup>2</sup>C-bus. Thus, the TPT29555 can remain a simple slave device. The power-on reset sets the registers to their default values and initializes the device state machine.

All input/output pins have internal weak pull-up resistors to remove external components. Three hardware pins (A0, A1, A2) select the fixed I<sup>2</sup>C-bus address and allow up to eight devices to share the same I<sup>2</sup>C-bus.

TPT29555 is available in TSSOP24 and QFN24 package, and is characterized from  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ .

## Function Block Diagram



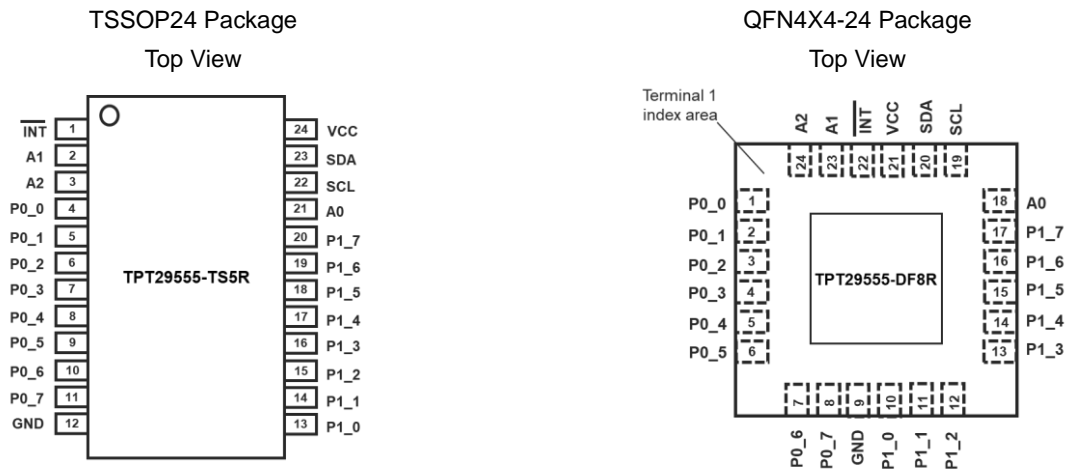
## Table of Contents

<b>Features</b> .....	1
<b>Applications</b> .....	1
<b>Description</b> .....	1
<b>Function Block Diagram</b> .....	1
<b>Revision History</b> .....	3
<b>Pin Configuration and Functions</b> .....	4
Pin Functions.....	4
<b>Specifications</b> .....	6
Absolute Maximum Ratings.....	6
ESD, Electrostatic Discharge Protection .....	6
Recommended Operating Conditions .....	6
Thermal Information .....	7
Electrical Characteristics .....	8
I <sup>2</sup> C Interface Timing Requirements .....	10
Switching Characteristics .....	11
Typical Performance Characteristics.....	12
<b>Detailed Description</b> .....	13
Overview.....	13
Function Block Diagram .....	13
Feature Description .....	14
<b>Tape and Reel Information</b> .....	17
<b>Package Outline Dimensions</b> .....	18
TS5R (TSSOP24).....	18
QF8R (QFN4X4-24L) .....	19
<b>Order Information</b> .....	20
<b>IMPORTANT NOTICE AND DISCLAIMER</b> .....	21

## Revision History

Date	Revision	Notes
2020-06-12	Rev.Pre.0	Initial Version
2021-06-15	Rev.A0	First release version
2021-12-14	Rev.A1	Added Standard mode timing requirements
2022-01-29	Rev.A2	Fixed the typo of ICC unit in page 9 Fixed the typo of pin function and outline of QFN package
2023-08-07	Rev.A3	Fixed the typo in page 16

## Pin Configuration and Functions



## Pin Functions

Pin			I/O	Description
Name	TSSOP24	QFN4X4-24		
A0	21	18	Input	Address input 0. Connect directly to VCC or ground
A1	2	23	Input	Address input 1. Connect directly to VCC or ground
A2	3	24	Input	Address input 2. Connect directly to VCC or ground
GND	12	9	GND	Ground
$\overline{\text{INT}}$	1	22	Output	Interrupt output. Connect to VCC through a pull-up resistor
P0_0	4	1	I/O	P-port I/O. Push-pull design structure. At power on, P0_0 is configured as an input
P0_1	5	2	I/O	P-port I/O. Push-pull design structure. At power on, P0_1 is configured as an input
P0_2	6	3	I/O	P-port I/O. Push-pull design structure. At power on, P0_2 is configured as an input
P0_3	7	4	I/O	P-port I/O. Push-pull design structure. At power on, P0_3 is configured as an input
P0_4	8	5	I/O	P-port I/O. Push-pull design structure. At power on, P0_4 is configured as an input
P0_5	9	6	I/O	P-port I/O. Push-pull design structure. At power on, P0_5 is configured as an input
P0_6	10	7	I/O	P-port I/O. Push-pull design structure. At power on, P0_6 is configured as an input
P0_7	11	8	I/O	P-port I/O. Push-pull design structure. At power on, P0_7 is configured as an input
P1_0	13	10	I/O	P-port I/O. Push-pull design structure. At power on, P1_0 is configured as an input

**Pin Functions (Continued)**

Pin			I/O	Description
Name	TSSOP24	QFN4X4-24		
P1_1	14	11	I/O	P-port I/O. Push-pull design structure. At power on, P1_1 is configured as an input
P1_2	15	12	I/O	P-port I/O. Push-pull design structure. At power on, P1_2 is configured as an input
P1_3	16	13	I/O	P-port I/O. Push-pull design structure. At power on, P1_3 is configured as an input
P1_4	17	14	I/O	P-port I/O. Push-pull design structure. At power on, P1_4 is configured as an input
P1_5	18	15	I/O	P-port I/O. Push-pull design structure. At power on, P1_5 is configured as an input
P1_6	19	16	I/O	P-port I/O. Push-pull design structure. At power on, P1_6 is configured as an input
P1_7	20	17	I/O	P-port I/O. Push-pull design structure. At power on, P1_7 is configured as an input
SCL	22	19	Input	Serial clock bus. Connect to VCC through a pull-up resistor
SDA	23	20	Input	Serial data bus. Connect to VCC through a pull-up resistor
VCC	24	21	Supply	Supply voltage

## Specifications

### Absolute Maximum Ratings

Parameter		Min	Max	Unit
V <sub>CC</sub>	Supply voltage	-0.5	6	V
V <sub>I</sub>	Input voltage	-0.5	6	V
V <sub>O</sub>	Output voltage	-0.5	6	V
I <sub>IK</sub>	Input clamp current, V <sub>I</sub> < 0		-20	mA
I <sub>OK</sub>	Output clamp current, V <sub>O</sub> < 0		-20	mA
I <sub>IOK</sub>	Input-output clamp current, V <sub>O</sub> < 0 or V <sub>O</sub> > V <sub>CC</sub>		±20	mA
I <sub>OL</sub>	Continuous output low current, V <sub>O</sub> = 0 to V <sub>CC</sub>		50	mA
I <sub>OH</sub>	Continuous output high current, V <sub>O</sub> = 0 to V <sub>CC</sub>		-50	mA
I <sub>CC</sub>	Continuous current through GND		-250	mA
	Continuous current through V <sub>CC</sub>		160	mA
T <sub>J</sub>	Maximum Junction Temperature		125	°C
T <sub>stg</sub>	Storage temperature	-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. Exposure to any Absolute Maximum Rating condition for extended periods may affect device reliability and lifetime.

(2) This data was taken with the JEDEC low effective thermal conductivity test board.

(3) This data was taken with the JEDEC standard multilayer test boards.

### ESD, Electrostatic Discharge Protection

Symbol	Parameter	Condition	Minimum Level	Unit
HBM	Human Body Model ESD	ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±4	kV
CDM	Charged Device Model ESD	ANSI/ESDA/JEDEC JS-002 <sup>(2)</sup>	±1.5	kV

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### Recommended Operating Conditions

Parameter		Min	Max	Unit	
V <sub>CC</sub>	Supply voltage	1.65	5.5	V	
V <sub>IH</sub>	High-level input voltage	SCL, SDA	0.7 × V <sub>CC</sub>	V <sub>CC</sub>	V
		A2 ~ A0, P0_7 ~ P0_0, P1_7 ~ P1_0	0.7 × V <sub>CC</sub>	5.5	V
V <sub>IL</sub>	Low-level input voltage	SCL, SDA	-0.5	0.3 × V <sub>CC</sub>	mV
		A2 ~ A0, P0_7 ~ P0_0, P1_7 ~ P1_0	-0.5	0.3 × V <sub>CC</sub>	mV
I <sub>OH</sub>	High-level output current	P0_7 ~ P0_0, P1_7 ~ P1_0	-10	mA	
I <sub>OL</sub>	Low-level output current	P0_7 ~ P0_0, P1_7 ~ P1_0	25	mA	
		INT <sub>1</sub> , SDA	6	mA	
T <sub>A</sub>	Operating Temperature Range	-40	85	°C	

**Thermal Information**

Package Type	$\theta_{JA}$	$\theta_{JC}$	Unit
TSSOP24	68	21	°C/W
QFN24	60	25	°C/W

### Electrical Characteristics

All test conditions:  $V_{CC} = 1.65\text{ V} \sim 5.5\text{ V}$ ,  $T_A = -40^\circ\text{C} \sim +85^\circ\text{C}$ , unless otherwise noted.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
<b>Input Electrical Specifications</b>						
$V_{POR}$	Power-on reset voltage, $V_{CC}$ rising	$V_I = V_{CC}$ or GND; $I_o = 0\text{ mA}$		1.25	1.45	V
	Power-on reset voltage, $V_{CC}$ falling	$V_I = V_{CC}$ or GND; $I_o = 0\text{ mA}$	0.8	1.2		V
$I_{OL}$	LOW-level output current, SDA	$V_{OL} = 0.4\text{ V}$ ; $V_{CC} = 1.65\text{ V}$ to $5.5\text{ V}$	3			mA
	LOW-level output current, INT	$V_{OL} = 0.4\text{ V}$ ; $V_{CC} = 1.65\text{ V}$ to $5.5\text{ V}$	3			mA
	LOW-level output current, P port	$V_{OL} = 0.5\text{ V}$ ; $V_{CC} = 1.65\text{ V}$	8			mA
		$V_{OL} = 0.5\text{ V}$ ; $V_{CC} = 2.3\text{ V}$	8			mA
		$V_{OL} = 0.5\text{ V}$ ; $V_{CC} = 3.0\text{ V}$	8			mA
		$V_{OL} = 0.5\text{ V}$ ; $V_{CC} = 4.5\text{ V}$	8			mA
	LOW-level output current, P port	$V_{OL} = 0.7\text{ V}$ ; $V_{CC} = 1.65\text{ V}$	10			mA
		$V_{OL} = 0.7\text{ V}$ ; $V_{CC} = 2.3\text{ V}$	10			mA
		$V_{OL} = 0.7\text{ V}$ ; $V_{CC} = 3.0\text{ V}$	10			mA
		$V_{OL} = 0.7\text{ V}$ ; $V_{CC} = 4.5\text{ V}$	10			mA
$V_{OH}$	HIGH-level output voltage, P port	$I_{OH} = -8\text{ mA}$ ; $V_{CC} = 1.65\text{ V}$	1.2			V
		$I_{OH} = -8\text{ mA}$ ; $V_{CC} = 2.3\text{ V}$	1.8			V
		$I_{OH} = -8\text{ mA}$ ; $V_{CC} = 3.0\text{ V}$	2.6			V
		$I_{OH} = -8\text{ mA}$ ; $V_{CC} = 4.75\text{ V}$	4.1			V
	HIGH-level output voltage, P port	$I_{OH} = -10\text{ mA}$ ; $V_{CC} = 1.65\text{ V}$	1.0			V
		$I_{OH} = -10\text{ mA}$ ; $V_{CC} = 2.3\text{ V}$	1.7			V
		$I_{OH} = -10\text{ mA}$ ; $V_{CC} = 3.0\text{ V}$	2.5			V
		$I_{OH} = -10\text{ mA}$ ; $V_{CC} = 4.75\text{ V}$	4.0			V
$I_I$	Input current: A0, A1, A2;	$V_{CC} = 1.65\text{ V}$ to $5.5\text{ V}$ , $V_I = V_{CC}$ or GND	-1		1	$\mu\text{A}$
	Input current: SCL, SDA	$V_{CC} = 1.65\text{ V}$ to $5.5\text{ V}$ , $V_I = V_{CC}$ or GND	-1		1	$\mu\text{A}$
$I_{IH}$	HIGH-level input current: P port	$V_I = V_{CC}$ ; $V_{CC} = 1.65\text{ V}$ to $5.5\text{ V}$			1	$\mu\text{A}$
$I_{IL}$	LOW-level input current: P port	$V_I = \text{GND}$ ; $V_{CC} = 1.65\text{ V}$ to $5.5\text{ V}$			-100	$\mu\text{A}$

(1) 100% tested at  $T_A = 25^\circ\text{C}$ .

(2) Parameters are provided by lab bench test and design simulation.



**Electrical Characteristics (Continued)**

 All test conditions:  $V_{CC} = 1.65\text{ V} \sim 5.5\text{ V}$ ,  $T_A = -40^\circ\text{C} \sim +85^\circ\text{C}$ , unless otherwise noted.

Symbol	Parameter	Conditions	Min	Typ	Max	Unit	
I <sub>CC</sub>	Supply current	Active mode, I <sub>O</sub> = 0 mA; I/O = inputs; f <sub>SCL</sub> = 400 kHz	V <sub>CC</sub> = 5.5 V		16	30	μA
			V <sub>CC</sub> = 3.6 V		9	20	μA
			V <sub>CC</sub> = 2.7 V		6.2	15	μA
			V <sub>CC</sub> = 1.95 V		4.2	10	μA
		Standby Mode, input low, I <sub>O</sub> = 0 mA; I/O = inputs; f <sub>SCL</sub> = 0 kHz	V <sub>CC</sub> = 5.5 V		0.90	1.5	mA
			V <sub>CC</sub> = 3.6 V		0.48	1.3	mA
			V <sub>CC</sub> = 2.7 V		0.43	1.0	mA
			V <sub>CC</sub> = 1.95 V		0.31	0.9	mA
		Standby Mode, input high, I <sub>O</sub> = 0 mA; I/O = inputs; f <sub>SCL</sub> = 0 kHz	V <sub>CC</sub> = 5.5 V		2.64	3.5	μA
			V <sub>CC</sub> = 3.6 V		1.55	2.3	μA
			V <sub>CC</sub> = 2.7 V		1.07	1.6	μA
			V <sub>CC</sub> = 1.95 V		0.68	1.2	μA
C <sub>i</sub>	Input capacitance	V <sub>I</sub> = V <sub>CC</sub> or GND; V <sub>CC</sub> = 1.65 V to 5.5 V <sup>(2)</sup>		3		pF	
C <sub>io</sub>	Input/output capacitance	V <sub>I/O</sub> = V <sub>CC</sub> or GND; V <sub>D</sub> = 1.65 V to 5.5 V <sup>(2)</sup>		3		pF	
		V <sub>I/O</sub> = V <sub>CC</sub> or GND; V <sub>CC</sub> = 1.65 V to 5.5 V <sup>(2)</sup>		5		pF	

 (1) 100% tested at T<sub>A</sub> = 25°C.

(2) Parameters are provided by lab bench test and design simulation.

### I<sup>2</sup>C Interface Timing Requirements

Over recommended operating free-air temperature range, unless otherwise noted.

Symbol	Description	Conditions	Standard Mod		Fast Mode		Unit
			Min	Max	Min	Max	
fsc1	I <sup>2</sup> C clock frequency		0	100	0	400	kHz
tsch	I <sup>2</sup> C clock high time		4		0.6		μs
tscl	I <sup>2</sup> C clock low time		4.7		1.3		μs
tsp	I <sup>2</sup> C spike time			50		50	ns
tsds	I <sup>2</sup> C serial-data setup time		250		100		ns
tsdh	I <sup>2</sup> C serial-data hold time		10		10		ns
ticr	I <sup>2</sup> C input rise time			1000	20	300	ns
ticf	I <sup>2</sup> C input fall time			300	$20 \times (V_{CC} / 5.5 \text{ V})$	300	ns
tocf	I <sup>2</sup> C output fall time	10-pF to 400-pF bus		300	$20 \times (V_{CC} / 5.5 \text{ V})$	300	ns
tbuf	I <sup>2</sup> C bus free time between stop and start		4.7		1.3		μs
tsts	I <sup>2</sup> C start or repeated start condition setup		4.7		0.6		μs
tsth	I <sup>2</sup> C start or repeated start condition hold		4		0.6		μs
tsps	I <sup>2</sup> C stop condition setup		4		0.6		μs
tvd(data)	Valid data time	SCL low to SDA output valid		3.5		0.9	μs
tvd(ack)	Valid data time of ACK condition	ACK signal from SCL low to SDA (out) low		3.5		0.9	μs
Cb	I <sup>2</sup> C bus capacitive load			400		400	pF

### Switching Characteristics

Over recommended operating free-air temperature range,  $C_L \leq 100$  pF, unless otherwise noted.

Symbol	Description	From (Input)	To (Output)	Standard Mod		Fast Mode		Unit
				Min	Max	Min	Max	
tiv	Interrupt valid time	P port	INT		4		4	$\mu$ s
tir	Interrupt reset delay time	SCL	INT		4		4	$\mu$ s
tpv	Output data valid; For $V_{CC} = 2.3$ V ~ 5.5 V	SCL	P port		400		400	ns
	Output data valid; For $V_{CC} = 1.65$ V ~ 2.3 V				400		400	ns
tps	Input data setup time	P port	SCL	15		15		ns
tph	Input data hold time	P port	SCL	1		1		$\mu$ s

### Parameter measurement waveforms

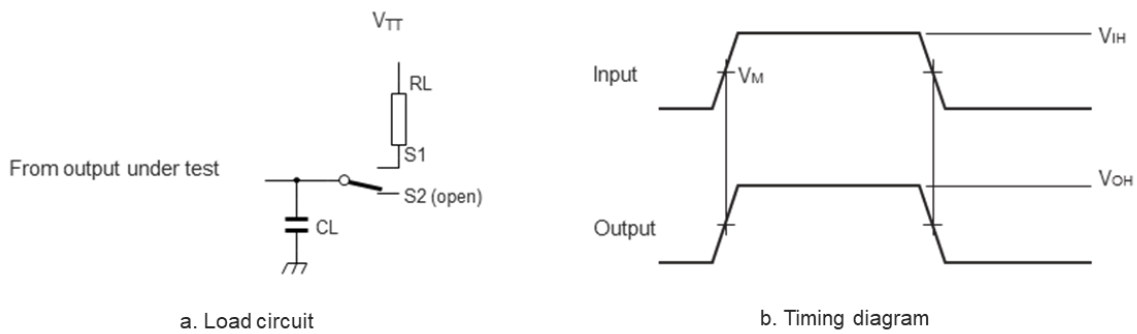
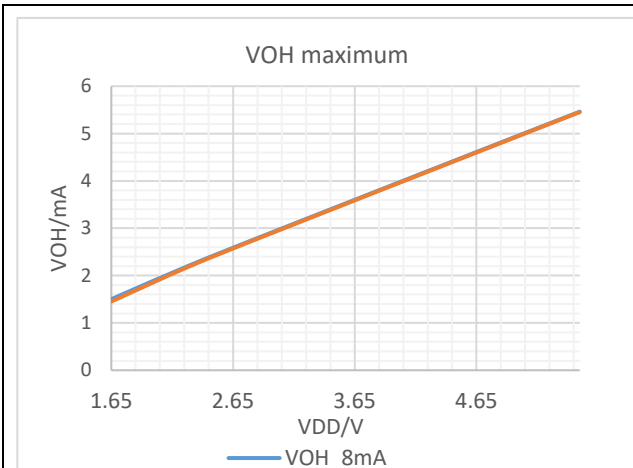
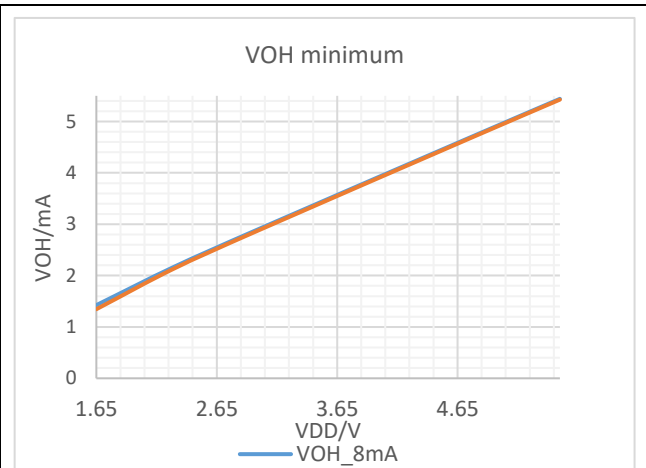


Figure 1 Load Circuit for Outputs

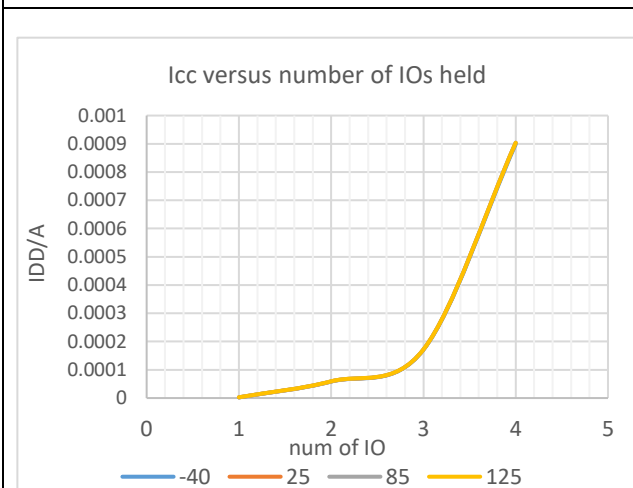
**Typical Performance Characteristics**



**Figure 2 Voh maximum measurement**



**Figure 3 Voh minimum measurement**



**Figure 4 Icc versus number of IOS measurement**

## Detailed Description

### Overview

The TPT29555 is a 16-bit GPIO expander with interrupt and builds in 100Kohm pull-up resistors for each IO port. The power supplier voltage range is from 1.65 V to 5.5 V that allows the TPT29555 to interconnect with 1.8-V microcontrollers.

The TPT29555 contains the register set of two pairs of 8-bit Configuration, Input, Output, and Polarity Inversion registers. The open-drain interrupt (INT) output is changeable when any input state changes from its related register state and is used to indicate the system master that an input state has changed. INT can be connected to the interrupt input of a microcontroller. By sending an interrupt signal on this line, the remote I/O can inform the microcontroller if there is incoming data on its ports without having to communicate via the I<sup>2</sup>C-bus. Thus, the TPT29555 can remain a simple slave device. The power-on reset sets the registers to their default values and initializes the device state machine.

All input/output pins have internal weak pull-up resistors to remove external components. Three hardware pins (A0, A1, A2) select the fixed I<sup>2</sup>C-bus address and allow up to eight devices to share the same I<sup>2</sup>C-bus.

### Function Block Diagram

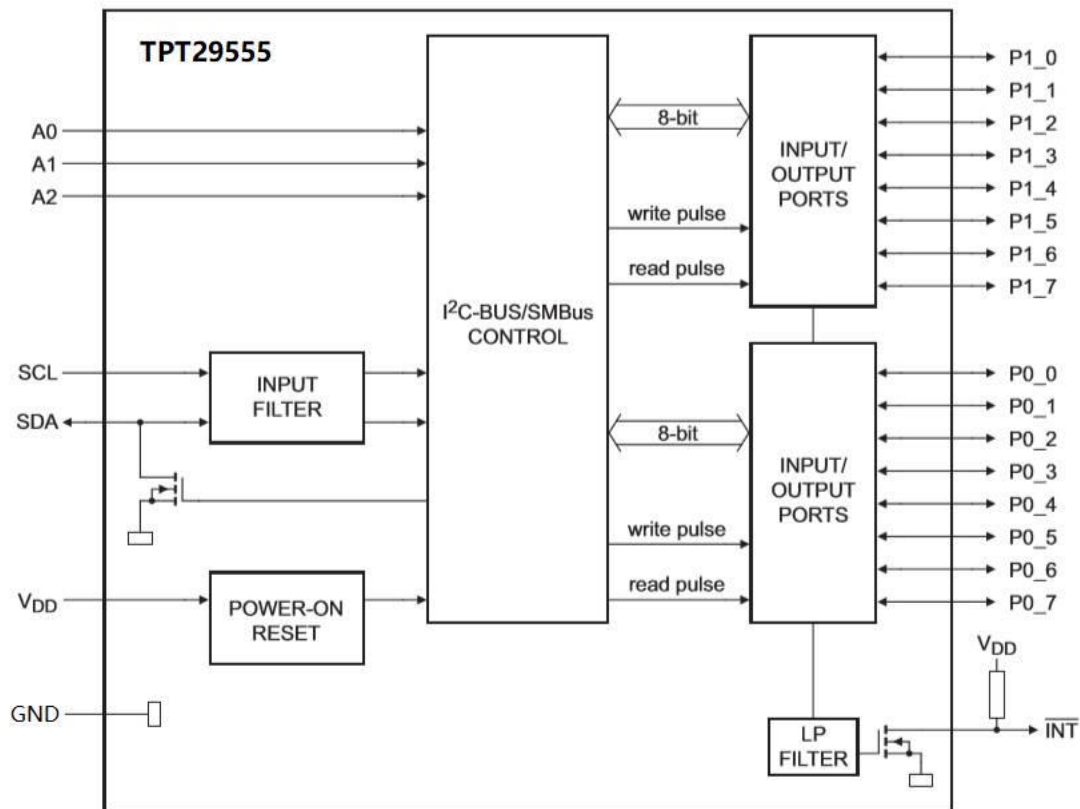


Figure 5 Function Block Diagram

### Feature Description

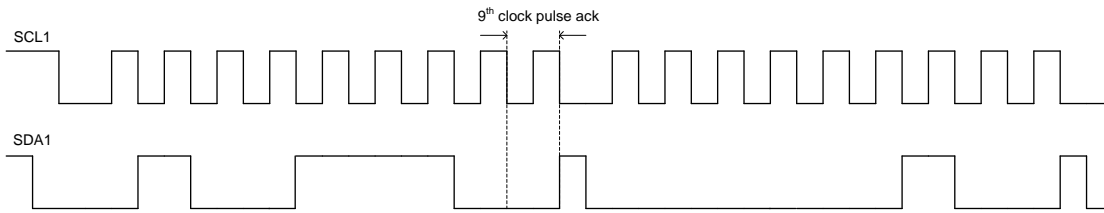


Figure 6 I<sup>2</sup>C BUS (1.65 V ~ 5.5 V) waveform

### Device Address

Following a START condition, the bus master must output the address of the slave it is accessing. All input/output pins have internal weak pull-up resistors to remove external components. Three hardware pins (A0, A1, A2) select the fixed I<sup>2</sup>C-bus address and allow up to eight devices to share the same I<sup>2</sup>C-bus. To conserve power, address pins (A0, A1, A2) must be pulled HIGH or LOW. The address of the TPT29555 is shown as below.

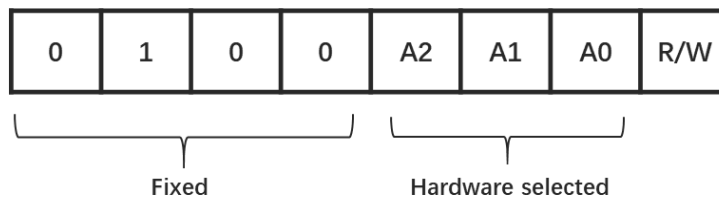


Figure 7 Slave Device Address

### Control Register

#### Command byte

The command byte is the first byte to follow the address byte during a write transmission. It is used as a pointer to determine which of the following registers will be written or read.

Table 1 Command Byte Description

Command	Register
0	Input port 0
1	Input port 1
2	Output port 0
3	Output port 1
4	Polarity Inversion port 0
5	Polarity Inversion port 1
6	Configuration port 0
7	Configuration port 1

**Register 0 and 1: Input port registers**

This register is an input-only port, which means the incoming logic levels of the pins, regardless of whether the pin is defined as an input or an output by Register 3 (output port 1), and writes to this register have no effect.

The default value 'X' is determined by the externally logic level.

**Table 2 Input Port 0 Register**

Bit	7	6	5	4	3	2	1	0
Symbol	I0.7	I0.6	I0.5	I0.4	I0.3	I0.2	I0.1	I0.0
Default	X	X	X	X	X	X	X	X

**Table 3 Input Port 1 Register**

Bit	7	6	5	4	3	2	1	0
Symbol	I1.7	I1.6	I1.5	I1.4	I1.3	I1.2	I1.1	I1.0
Default	X	X	X	X	X	X	X	X

**Register 2 and 3: Output port registers**

This register is an output-only port, which means the outgoing logic levels of the pins defined as outputs by Register 6 (Configuration port 0) and 7 (Configuration port 1). Bit values in this register have no effect on pins defined as inputs. In fact, the value reading from this register is in the flip-flop controlling the output selection, not the actual pin value.

**Table 4 Output Port 0 Register**

Bit	7	6	5	4	3	2	1	0
Symbol	O0.7	O0.6	O0.5	O0.4	O0.3	O0.2	O0.1	O0.0
Default	1	1	1	1	1	1	1	1

**Table 5 Output Port 1 Register**

Bit	7	6	5	4	3	2	1	0
Symbol	O1.7	O1.6	O1.5	O1.4	O1.3	O1.2	O1.1	O1.0
Default	1	1	1	1	1	1	1	1

**Register 4 and 5: Polarity Inversion registers**

This register allows the user to invert the polarity of the input port register data. If a bit in this register is set (written with '1'), the input port data polarity is inverted. If a bit in this register is cleared (written with '0'), the input port data polarity is retained.

**Table 6 Polarity Inversion port 0 Register**

Bit	7	6	5	4	3	2	1	0
Symbol	N0.7	N0.6	N0.5	N0.4	N0.3	N0.2	N0.1	N0.0
Default	0	0	0	0	0	0	0	0

**Table 7 Polarity Inversion port 1 Register**

Bit	7	6	5	4	3	2	1	0
Symbol	N1.7	N1.6	N1.5	N1.4	N1.3	N1.2	N1.1	N1.0
Default	0	0	0	0	0	0	0	0

**Register 6 and 7: Configuration registers**

This register configures the directions of the I/O pins. If a bit in this register is set (written with '1'), the corresponding port pin is enabled as an input with a high-impedance output driver. If a bit in this register is cleared (written with '0'), the corresponding port pin is enabled as an output. Note that there is a high-value resistor tied to V<sub>DD</sub> at each pin. At reset, the device's ports are inputs with a pull-up to V<sub>DD</sub>.

**Table 8 Configuration port 0 Register**

Bit	7	6	5	4	3	2	1	0
Symbol	C0.7	C0.6	C0.5	C0.4	C0.3	C0.2	C0.1	C0.0
Default	1	1	1	1	1	1	1	1

**Table 9 Configuration port 1 Register**

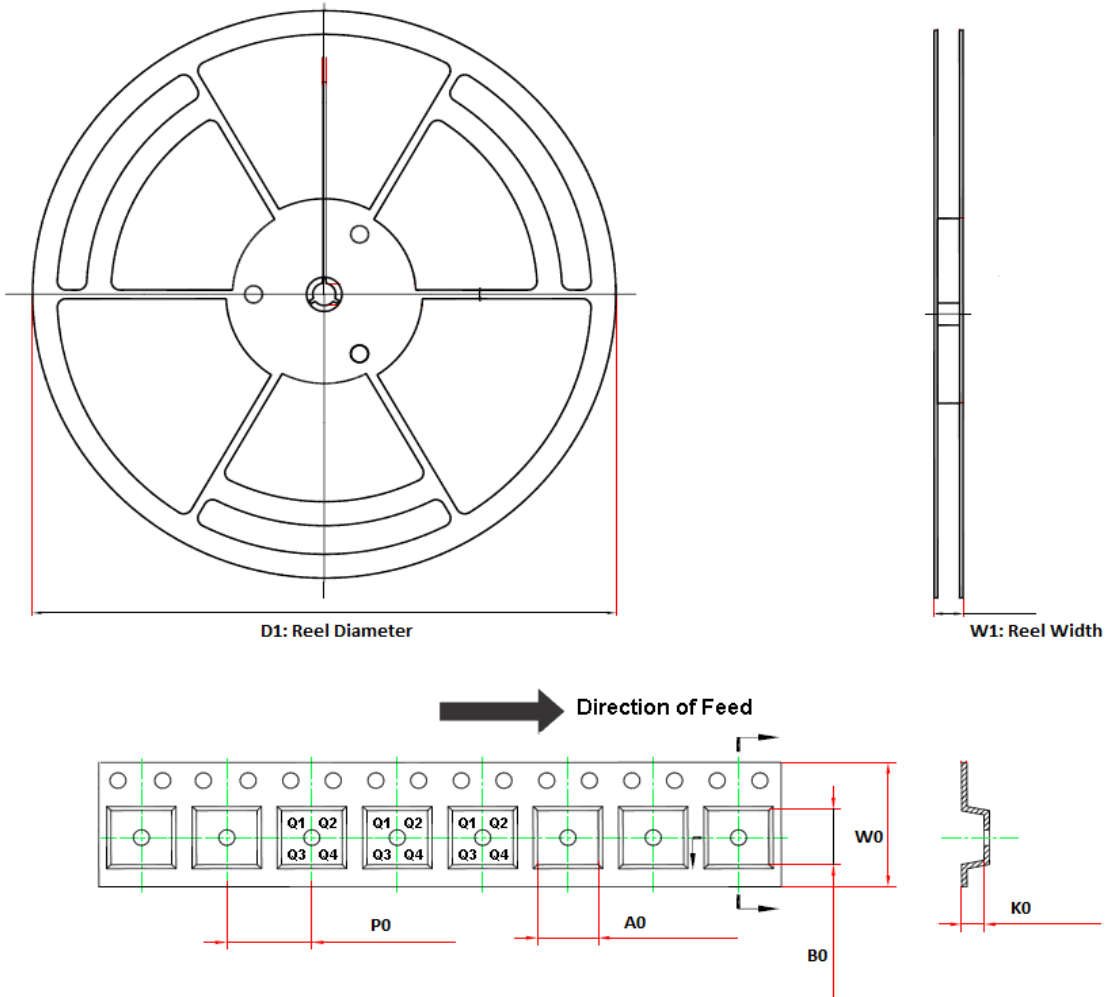
Bit	7	6	5	4	3	2	1	0
Symbol	C1.7	C1.6	C1.5	C1.4	C1.3	C1.2	C1.1	C1.0
Default	1	1	1	1	1	1	1	1

**Reserved register**

As the part of SMBUS function, the register 0X0C of TPT29555 is reserved. Any operation of these registers is not suggested.



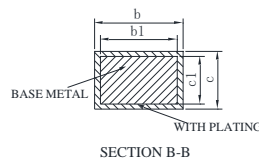
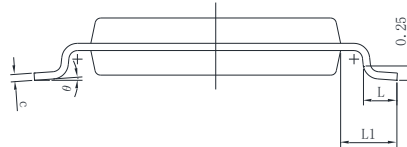
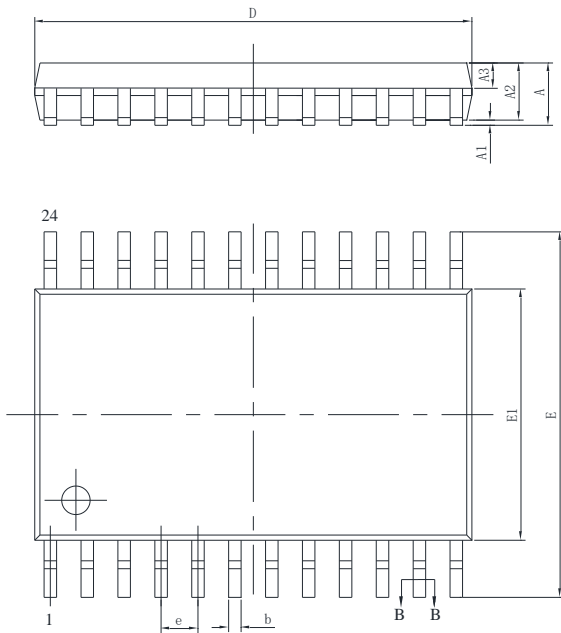
### Tape and Reel Information



Order Number	Package	D1 (mm)	W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P0 (mm)	W0 (mm)	Pin1 Quadrant
TPT29555-TS5R	24-Pin TSSOP	330	22.4	6.8	8.3	1.6	8	16	Q1
TPT29555-QF8R	24-Pin QFN	330	17.6	4.3	4.3	1.1	8	12	Q1

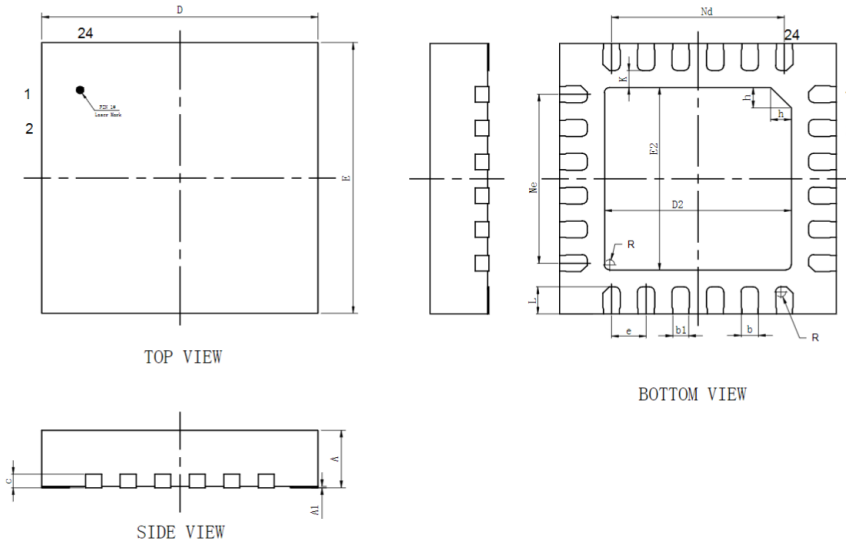
### Package Outline Dimensions

#### TS5R (TSSOP24)



SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	—	—	1.20
A1	0.05	—	0.15
A2	0.80	1.00	1.05
A3	0.39	0.44	0.49
b	0.20	—	0.29
b1	0.19	0.22	0.25
c	0.13	—	0.18
c1	0.12	0.13	0.14
D	7.70	7.80	7.90
E	6.20	6.40	6.60
E1	4.30	4.40	4.50
e	0.65BSC		
L	0.45	0.60	0.75
L1	1.00BSC		
θ	0	—	8°

QF8R (QFN4X4-24L)



SYMBOL	MILLIMETER		
	MIN	NOM	MAX
A	0.80	0.85	0.90
A1	0	0.02	0.05
b	0.20	0.25	0.30
b1	0.23REF		
c	0.203REF		
D	3.90	4.00	4.10
D2	2.65	2.70	2.75
e	0.50BSC		
Nd	2.50BSC		
Ne	2.50BSC		
E	3.90	4.00	4.10
E2	2.65	2.70	2.75
L	0.35	0.40	0.45
h	0.25	0.30	0.35
K	0.25REF		
R	0.075REF		

## Order Information

Order Number	Operating Temperature Range	Package	Marking Information	MSL	Transport Media, Quantity	Eco Plan
TPT29555-TS5R	-40 to 85°C	24-Pin TSSOP	29555	MSL3	4,000	Green
TPT29555-QF8R	-40 to 85°C	24-Pin QFN	29555	MSL3	3,000	Green

**Green:** 3PEAK defines "Green" to mean RoHS compatible and free of halogen substances.

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